

GE  $Ax=b$ .  $A^{(1)} = [A|b] \rightarrow A^{(2)} \dots A^{(n-1)}$

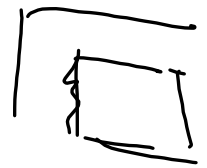
$k=1, 2, \dots, n-1$   $= [U; \tilde{b}]$

$$a_{ij}^{(k+1)} = a_{ij}^{(k)} - \frac{a_{ik}^{(k)}}{a_{kk}^{(k)}} \cdot a_{kj}^{(k)} \quad \begin{matrix} i=k, k+1, \dots, n \\ j=k+1, \dots, n+1 \end{matrix}$$

k-th step.  $n-k$  divisions

multiplication  $(n-k)(n-k)$

addition/subtraction  $(n-k)(n-k+1)$



1-st.  $(n-1)(n-1+1) + (n-1)$   
 $= (n-1)(n+1)$

2nd  $(n-2)(n)$

3rd  $(n-3)(n-1)$

$$\sum_{k=1}^{n-1} k(k+2) = \sum_{k=1}^{n-1} k^2 + \sum_{k=1}^{n-1} 2k$$

handbook  $= \frac{(n-1)n(2n-1)}{6} + 2 \frac{(1+n-1)(n-1)}{2}$

$$= \frac{1}{3}n^3 + ( )n^2 + ( )n$$

$$= O(n^3/3)$$

$n = 10^3$

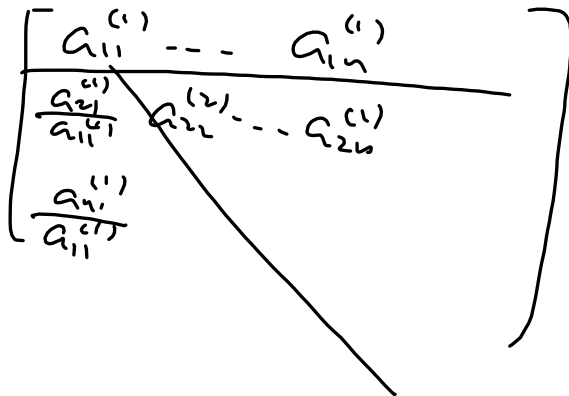
$n^3 = 10^9$

$320 \times 320 \checkmark$   
 $640 \times 640 \checkmark$

$2480 \times 2480 \times$

Storage.  $A^{(1)} \rightarrow A^{(2)} \dots, A^{(n-1)}$

Over-write.



for  $k=1, n-1$

for  $i=k: n$

$$a_{ik} := \frac{a_{ik}}{a_{kk}}$$

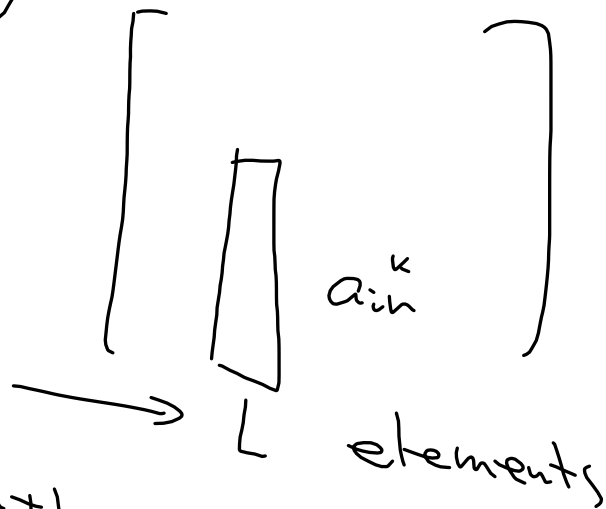
for  $j=k+1: n+1$

$$a_{ij} := a_{ij} - a_{ik} * a_{kj}$$

end

end

end



programming

When we finish, we get

$$A = LU$$

$$L = \begin{bmatrix} 1 & & & & \\ a_{21} & 1 & & & \\ a_{31} & a_{32} & \dots & & \\ & & & \ddots & \\ a_{n1} & \dots & \dots & \dots & a_{nn} \end{bmatrix}$$

1.

$$U = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ & a_{22} & \dots & a_{2n} \\ & & \ddots & \\ & & & a_{nn} \end{bmatrix}$$

2. Use backward substitution to solve  $Ax = b$  original problem

$$x_n = a_{n,n+1} / a_{nn}$$

for  $i = n-1, \dots, 1$

$$x_i = a_{i,n+1}$$

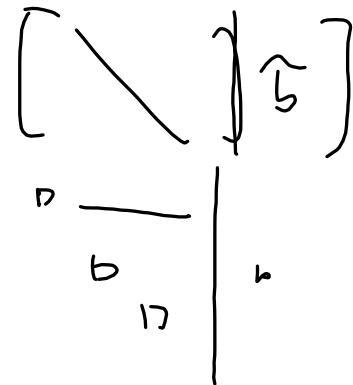
for  $j = i+1, n$

$$x_i = x_i - a_{ij} \cdot x_j$$

end

$$x_i = x_i / a_{ii}$$

end



$$x_i = a_{i,n+1} - \sum_{j=i+1}^n a_{ij} x_j$$

(3)  $\det(A) = a_{11} a_{22} \dots a_{nn}$

$a_{ii}$ 's are changed ones.

When will GE fail?  $a_{ii} = 0$ .

Does it mean  $\det(A) = 0$ ,  $A$  is singular?

No,

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$\det(A) = -1$ ,  
 $A^{-1}$  exist.

$$A = \begin{bmatrix} \sigma & 1 \\ 1 & 1 \end{bmatrix} \rightarrow$$

$$\begin{bmatrix} 1 & 0 \\ \sigma & 1 \end{bmatrix} \begin{bmatrix} \sigma & 1 \\ 0 & 1 - \frac{1}{\sigma} \end{bmatrix} = \begin{bmatrix} \sigma & 1 \\ 1 & 1 \end{bmatrix} \checkmark$$

$$fl\left(\frac{1}{\sigma}\right) \leftarrow \frac{1}{\sigma(1+\delta_1)} (1+\delta_2)$$

Switch rows does not change the problem.

Before GE, check

$$|a_{l1}| \geq |a_{i1}|, \quad i=1, 2, \dots, n.$$

$l=1$ ; pivot =  $\text{abs}(a_{(1,1)})$ ;  $(a_{11})$   
 for  $i=2:n$   $l \rightarrow k$   
 if ( $\text{abs}(a_{(i,1)}) > \text{pivot}$  general  
     pivot =  $\text{abs}(a_{(i,1)})$  case  
      $l=i$ ;  
 end <sup>end</sup>

After finish,  $l$  is the index of row that has the largest magnitude.  
 $\text{pivot} = \max |a_{i,1}|$

Switch

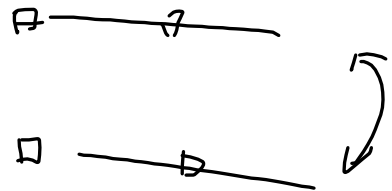
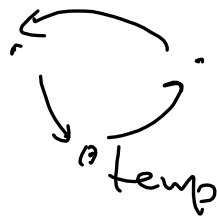
for  $j=1: n+1$

tmp =  $a(1, j)$ ;

$a(1, j) = a(l, j)$ ;

$a(l, j) = tmp$

end



$l \rightarrow k$ .

Can be done using a vector operation

$b = a(:, j)$ ,  $j$ -th column of  $A$ .