

Perturbation Theory for algebraic
eigenvalue problems \rightarrow Sensitivity.

$$\lambda_i(\epsilon) \quad |\lambda_i(A) - \lambda_i(A+E)| \leq \frac{\|E\|}{|y_i^H x_i|}$$

$$A x_i = \lambda_i x_i,$$

right

$$y_i^H A = \lambda_i y_i^H$$

left

$$\text{If } A = A^T,$$

$$x_i = y_i,$$

$$\|x_i\| = 1$$

$$\|y_i\| = 1$$

$$\text{If } A = A^H, \quad Q^H A Q = D$$

or A is normal $AA^H = A^H A, \rightarrow$

$$Q^H A Q = D \quad Q^H Q = I$$

$$\max_i |\lambda_i(A) - \lambda_i(A+E)| \leq \|E\|$$

Ex: 1

$$A = \begin{bmatrix} 4 & 1 & & & \\ & 1 & -4 & 1 & \\ & & & 8 & 1 \\ & & & & 20 \end{bmatrix} \quad \|E\| \leq \frac{1}{4}$$

$$\bar{\lambda}_i = \lambda_i(A+E)$$

$$20 - 1 - \frac{1}{4} \leq \bar{\lambda}_1 \leq 20 + 1 + \frac{1}{4}$$

$$8 - 2 - \frac{1}{4} \leq \lambda_2 \leq 8 + 2 + \frac{1}{4}$$

$$4 - 1 - \frac{1}{4} \leq \lambda_{3,4} \leq 4 + 1 + \frac{1}{4}$$

$$-4 - 2 - \frac{1}{4} \leq \lambda_{3,4} \leq -4 + 2 + \frac{1}{4}$$

For general matrices.

$$A \sim \begin{bmatrix} J_1 & & & \\ & J_2 & & \\ & & \ddots & \\ 0 & & & J_p \end{bmatrix} = J, \quad J_k = \begin{bmatrix} \lambda_k & & \\ & \lambda_k & \\ & & \ddots \\ & & & \lambda_k \end{bmatrix}_{N_k}$$

$$S^{-1}AS = J$$

$$J_{k+1} = \begin{bmatrix} \lambda_k \end{bmatrix}$$

$$|\lambda_k(A) - \lambda_k(A+E)| \leq C \|E\|^{1/N_k}$$

e.g. $\|E\| \leq 10^{-5}, \quad N_k = 3,$

$$|\lambda_i(A) - \lambda_i(A+E)| \leq 10^{-5}$$

Ex:

$$B = \begin{pmatrix} 4 & & & \\ & 4 & & \\ & & 5 & -1 \\ & & & 5 & 4 \\ & & & & 5 \end{pmatrix}$$

$$\lambda_i = 4$$

$$|\lambda_i(A) - \lambda_i(A+E)| \leq C \|E\|$$

$$\lambda_i = 5$$

$$|\lambda_i(A) - \lambda_i(A+E)| \leq C \|E\|^{1/3}$$

Solving least squares problems.

Over-determined. $Ax = b$,

$A \in \mathbb{R}^{m \times n}$, $m \geq n$, $\text{rank}(A) = n$.

Ex: Curve fitting

... sample

t	t_0	t_1	...	t_m
y	y_0	y_1	...	y_m

$y(t)$

$y(t) = a_0$

or

$y(t) = a_0 + a_1 t$

$y(t) = a_0 \cos t + a_1 \sin t$

$y(t) = a_0 + a_1 t + a_2 t^2$

$\{a_i\}_{i=0}^n$ are coefficients to be determined

$y_h(t) = \sum_{i=0}^n a_i \underline{\underline{\phi_i(t)}}$

$\{\phi_i(t)\}$ basis
 a_i : coef.

$$y_n(t) = \sum_{i=0}^n a_i t^i, \text{ polynomial fit}$$

$$y_n(t_k) = \sum_{i=0}^n a_i t_k^i = y_k$$

$$n=0 \quad \begin{cases} a_0 = y_0 \\ a_0 = y_1 \\ \vdots \\ a_0 = y_m \end{cases} \quad \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} [a_0] = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_m \end{bmatrix} \quad (n+1)$$

$$n=1 \quad \begin{cases} a_0 + a_1 t_0 = y_0 \\ a_0 + a_1 t_1 = y_1 \\ \dots \\ a_0 + a_1 t_m = y_m \end{cases} \quad \begin{bmatrix} 1 & t_0 \\ 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_m \end{bmatrix}$$

$A \in \mathbb{R}^{(m+1) \times 2} \quad b \in \mathbb{R}^{m+1}$

In $A \in \mathbb{R}^{m \times n}$, $m > n$, $\text{rank}(A) = n$
 (general, there is no classical soln.
 i.e. There is no such an x^* that

$$Ax^* - b = 0$$

The best soln'

$$\|Ax^* - b\| = \min_{x \in \mathbb{R}^n} \|Ax - b\|$$

$r(x)$

1, 2, ∞ ,

$$\begin{aligned} \Leftrightarrow \|Ax^* - b\|_2^2 &= \min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2 \\ &= \min_{x \in \mathbb{R}^n} (Ax - b)^T (Ax - b) \\ &= \min_{x \in \mathbb{R}^n} \left\{ x^T A^T A x - x^T A^T b - b^T A x + b^T b \right\} \\ &= F(x_1, x_2, \dots, x_n) \end{aligned}$$

It's differentiable.

Quadratic form of $A^T A$

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2 = \min_{x \in \mathbb{R}^n} \max_{1 \leq i \leq n} \left| \frac{Ax - b}{x_i} \right|$$

$$\|Ax - b\|_2^2 = \underbrace{x^T A^T A x}_{f(x_1, x_2, \dots, x_n)} - \overset{y = \overset{\vee}{x^T A^T} b}{\underbrace{b^T A x}_{\overset{\vee}{x^T A^T} b}} + b^T b$$

$$\nabla F = \nabla x^T y = \nabla \sum x_i y_i = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

$$\underline{b^T A x} = (Ax)^T b = x^T A^T b$$

$$F(x) = x^T B x \quad \nabla F = 2 B x$$

$$= x^T \begin{bmatrix} a_{11}x_1 + \dots + a_{1n}x_n \\ a_{21}x_1 + \dots + a_{2n}x_n \\ \vdots \\ a_{n1}x_1 + \dots + a_{nn}x_n \end{bmatrix}$$

$$= x_1 a_{11}x_1 + \dots + x_1 a_{1n}x_n + x_2 a_{21}x_1 + \dots + x_2 a_{2n}x_n$$

$$= \sum a_{ij} x_i x_j \quad A = A^T$$

$$\nabla F = \begin{bmatrix} 2a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 \\ \vdots \end{bmatrix}$$

$$\nabla F = \nabla x^T A^T A x = 2 A^T A x$$

$$\nabla \|Ax - b\|_2^2 = 2 A^T A x - 2 A^T b = 0$$

$$\underline{A^T A x = A^T b} \quad \text{normal Eqn of } Ax = b$$

$R^{n \times n}$ $R^{n \times 1}$

$$Ax = b, \quad A \in \mathbb{R}^{m \times n}, \quad m > n,$$

$$\text{rank}(A) = n, \quad \text{full column rank.}$$

Well posedness $\min_{x \in \mathbb{R}^n} \|Ax - b\|_2$

$$F(x_1, x_2, \dots, x_n) \Leftrightarrow \min \|Ax - b\|_2^2$$

$$= x^T A^T A x - 2b^T A^T x + b^T b \geq 0$$

Existence: (A) Finite dimension + continuity

(B) $\underbrace{A^T A}_n x = A^T b$ RHS

$\forall x \in \mathbb{R}^n, x \neq 0, \underbrace{A^T A}_n x \neq 0$ Normal Equ $A^T A \in \mathbb{R}$

$$x^T A^T A x = (Ax)^T Ax = \|Ax\|_2^2$$

$A(:, i) =$ i -th column $x = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_n \end{bmatrix}$

$$Ax = \sum_{i=1}^n x_i A(:, i) \neq 0 \text{ if } \vec{x} \neq 0$$

Since A has full column rank, $A^T A$ is invertible.

Soln. exist and it's unique

$$x = (A^T A)^{-1} A^T b.$$

Exs

t	t ₀ ... t _m
y(t)	

$$y(t) = \sum_{i=0}^n a_i t^i$$

n=0 $y(t) = a_0$

$$A = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} \quad b = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_m \end{bmatrix}$$

$$A^T A x = A^T b$$

$$\begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} a_0 = \begin{bmatrix} 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} y_0 \\ \vdots \\ y_m \end{bmatrix}$$

$$(m+1) a_0 = \sum_{j=0}^m y_j$$

$$a_0 = \frac{1}{m+1} \sum_{j=0}^m y_j, \text{ average}$$

n=1 $y(t) \approx a_0 + a_1 t$

$$A = \begin{bmatrix} 1 & t_0 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \quad b = \begin{bmatrix} y_0 \\ \vdots \\ y_m \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 1 & \dots & 1 \\ t_0 & t_1 & \dots & t_m \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \\ t_0 \\ \vdots \\ t_m \end{bmatrix} \begin{bmatrix} y_0 \\ \vdots \\ y_m \end{bmatrix}$$

$$\begin{bmatrix} m+1 & \sum_{i=0}^m t_i \\ \sum_{i=0}^m t_i & \sum_{i=0}^m t_i^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} \sum_{i=0}^m y_i \\ \sum_{i=0}^m t_i y_i \end{bmatrix}$$

$$a_0 = \frac{\sum y_i \sum t_i^2 - \sum t_i \sum y_i t_i}{(m+1) \sum t_i^2 - (\sum t_i)^2}$$

$$a_1 = \frac{(m+1) \sum t_i y_i - \sum t_i \sum y_i}{(m+1) \sum t_i^2 - (\sum t_i)^2}$$

General n

$$A^T A = \begin{bmatrix} m+1 & \sum t_i & \sum t_i^2 \\ \sum t_i & \sum t_i^2 & \sum t_i^3 \\ \sum t_i^2 & \sum t_i^3 & \sum t_i^4 \end{bmatrix}$$

A^T

$$A^T b = \begin{bmatrix} \sum_{i=0}^m y_i \\ \sum t_i y_i \\ \sum t_i^2 y_i \end{bmatrix}$$

Extension: $y(t) = a_1 \cos t + b_1 \sin t$

$$A = \begin{bmatrix} \cos t_0 & \sin t_0 \\ \vdots & \vdots \\ \cos t_m & \sin t_m \end{bmatrix}, \quad y = \begin{bmatrix} y_0 \\ \vdots \\ y_m \end{bmatrix}$$

$$A^T A = \begin{bmatrix} \sum_{i=0}^m \cos^2 t_i & \sum \cos t_i \sin t_i \\ \times & \sum \sin^2 t_i \end{bmatrix}$$

$$A^T y = \begin{bmatrix} \sum_{i=0}^m (\cos t_i) y_i \\ \sum_{i=0}^m (\sin t_i) y_i \end{bmatrix}$$

Ex 4 $y(t) \approx a_1 e^{a_2 t}$

$$\log y(t) = \log a_1 + a_2 t$$

$$\widetilde{y}(t) = \widetilde{a}_1 + a_2 t$$

becomes a linear least squares problem.

$$\sqrt{\sum (b_i - \widetilde{a}_1 - a_2 t_j)^2}$$

QR method for least squares problem. Why:

We only use the normal Eqn approach if n is small to modest, $\text{Cond}(A)$ is small,

$$\text{Cond}_2(A^T A) = (\text{Cond}(A))^2$$

Eigenvalues of $A^T A$ and $A A^T$

$$A A^T x = \lambda x \quad x \neq 0$$

$\lambda(A A^T)$

$$A^T A (A^T x) = \lambda (A^T x) \quad \lambda \neq 0 \Rightarrow A^T x \neq 0$$

Solve $Ax = b$

$$A = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix}_{m \times n}$$

$$R_1 \in \mathbb{R}^{n \times n}, \det(R_1) \neq 0.$$

$$R_2 = 0$$

The least squares solution to this problem

$$\begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ \circ & r_{22} & \dots & r_{2n} \\ & & \dots & \\ & & & r_{nn} \end{bmatrix}$$

$$b_1 \in \mathbb{R}^{n \times 1}, b_2 \in \mathbb{R}^{m-n, 1}$$

$$b = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\begin{bmatrix} R_1 \\ 0 \end{bmatrix} x = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$x = R_1^{-1} b_1$$

$$\|x\|_2^2 = \sum x_i^2 = 0$$

$$\|b - Ax\|_2^2 = \left\| \begin{bmatrix} R_1 x - b_1 \\ -b_2 \end{bmatrix} \right\|_2^2 = \|R_1 x - b_1\|_2^2 + \|b_2\|_2^2$$

$$\min \|b - Ax\|_2^2 \quad x = R_1^{-1} b_1$$

QR method for least squares

problems.

$$Ax=b, A \in \mathbb{R}^{m \times n}, \text{rank}(A) = n$$

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2$$

Normal Eqn.

$$A^T A x = A^T b$$

S.P.D.

$$\text{Cond}_2(A^T A) = (\text{Cond}_2(A))^2$$

(ii) QR method

$$A = QR$$

Need n House

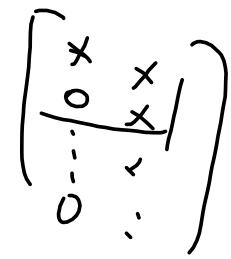
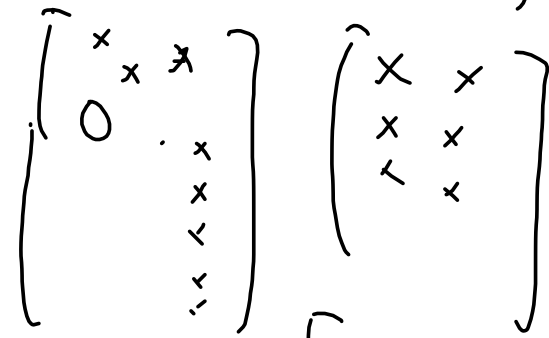
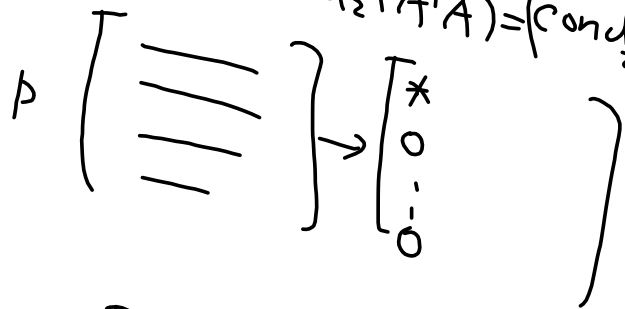
$$Ax=b$$

$$QRx=b, Q^H Q = I$$

$$Rx = Q^H b$$

$$\begin{bmatrix} R_1 \\ 0 \end{bmatrix} x = \begin{bmatrix} \tilde{b}_1 \\ \tilde{b}_2 \end{bmatrix}$$

$$x_{ls} = R_1^{-1} \tilde{b}_1$$



$$P_n \dots P_2 P_1 [A | b]$$

$$P_1 A = \begin{bmatrix} R_1 & \vdots & \hat{b}_1 \\ 0 & \vdots & \hat{b}_2 \end{bmatrix}$$

$R_1 x = \hat{b}_1$, backward subst.

Ex

Use the QR to solve $Ax = b$

t_i	1	2	3	4
y_i	0	1	-1	6

$$y(t) = a_0 + a_1 t$$

Find a_0, a_1

$A : b$

$$\begin{bmatrix} 1 & 1 & | & 0 \\ 1 & 2 & | & 1 \\ 1 & 3 & | & -1 \\ 1 & 4 & | & 6 \end{bmatrix}$$

$$P_1 [A : b] = \begin{bmatrix} -2 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$w = \frac{x-y}{\|x-y\|_2}$$

$$P_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$w = \frac{x-y}{\|x-y\|_2} = \begin{bmatrix} 3 \\ 1 \\ 1 \\ 1 \end{bmatrix} \frac{1}{\sqrt{12}}$$

$$P_1 = I - 2 \begin{bmatrix} 3 \\ 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 3 & 1 & 1 & 1 \end{bmatrix} / 12$$

$$P_1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \left(I - \frac{1}{6} \begin{bmatrix} 3 \\ 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 3 & 1 & 1 & 1 \end{bmatrix} \right) \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \\ = \begin{bmatrix} -5 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

$$P_1 b = P_1 \begin{bmatrix} 0 \\ 1 \\ -1 \\ 6 \end{bmatrix} = \begin{bmatrix} -3 \\ 0 \\ -2 \\ 5 \end{bmatrix}$$

$$P_1 [A; b] = \begin{bmatrix} -2 & -5 & 1 & -3 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & -2 \\ 0 & 2 & 1 & 5 \end{bmatrix} \quad \begin{matrix} 1 & 0 & 0 & 0 \\ 0 & & & \\ 0 & P_2 & & \\ 0 & & & \end{matrix}$$

$$W_2 = \begin{bmatrix} -\sqrt{5} \\ 1 \\ 2 \end{bmatrix} \sqrt{10}$$

$$P_2 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} \sqrt{5} \\ 0 \\ 0 \end{bmatrix}$$

$$P_2 P_1 [A; b] = \begin{bmatrix} -2 & -5 & 1 & -3 \\ 0 & \sqrt{5} & 1 & -18/\sqrt{5} \\ 0 & 0 & 1 & -8/5 \\ 0 & 0 & 0 & 9/5 \end{bmatrix}$$

$$\min \|Ax - b\| = \sqrt{\left(\frac{8}{5}\right)^2 + \left(\frac{9}{5}\right)^2}$$

x_1, x_2

$$x_2 = -18/5,$$

$$x_1 = \left(-3 + 5 \cdot \left(-\frac{18}{5} \right) \right) / -2;$$

SVD approach. For any $Ax=b$

e.g. $2x_1 + x_2 - 3x_3 = ?$ $A \in \mathbb{R}^{m \times n}$

$\text{rank}(A) = p$

$p \leq \min\{m, n\}$

SVD Thm:

Given any $A \in \mathbb{C}^{m \times n}$, there are two orthogonal $U \in \mathbb{C}^{m \times m}$, $U^H U = I$
 $V \in \mathbb{C}^{n \times n}$, $V^H V = V V^H = I = U U^H$

$A = U \Sigma V^H$ $\begin{matrix} U A V^H \\ U \end{matrix}$

$= U \begin{bmatrix} \sigma_1 & & & & & \\ & \sigma_2 & & & & \\ & & \ddots & & & \\ & & & \sigma_p & & \\ & & & & 0 & \\ & & & & & 0 \end{bmatrix} V^H$

$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p > 0$ are singular values of A .

$\|A\|_2 = \sigma_1$

Pseudo-inverse of A

$A^+ = V \begin{bmatrix} 1/\sigma_1 & & & & & \\ & 1/\sigma_2 & & & & \\ & & \ddots & & & \\ & & & 1/\sigma_p & & \\ & & & & 0 & \\ & & & & & 0 \end{bmatrix} U^H$

$A = BC$
 $A^+ = C^{-1} B^{-1}$

$\|A^+\|_2 = \frac{1}{\sigma_p}$

$\text{Cond}_2(A) = \frac{\max_{1 \leq i \leq p} \{\sigma_i(A)\}}{\min_{1 \leq i \leq p} \{\sigma_i(A)\}}$

σ_i^2 are eigenvalues of $A^H A$

Proof: $A = \underline{U \Sigma V^H}$ AA^H

$$A^H A = \frac{V \Sigma^H U^H}{A^H} U \Sigma V^H$$

A similarity transform

$$= V \Sigma^2 V^H = V \begin{bmatrix} \sigma_1^2 & & & \\ & \ddots & & \\ & & \sigma_p^2 & \\ & & & 0 \\ & & & & 0 \end{bmatrix} V^H$$