

Householder matrix

$$P = I - 2ww^T, \quad \|w\|_2 = 1$$

$$= I - \frac{2ww^T}{\|w\|_2^2}$$

Thm: $P = P^T, \quad P^T P = I, \quad P^{-1} = P^T$

P is an orthogonal matrix

$$P^T P = (I - 2ww^T)(I - 2ww^T)$$

$$= I - 2ww^T - 2ww^T + 4\underline{ww^T}ww^T \stackrel{=1}{=} I$$

Given $x \in \mathbb{R}^n$, $y \in \mathbb{R}^n$

Can we find an orthogonal matrix P such that

$$Px = y, \quad P^T = P^{-1}$$

True if $\|Px\|_2 = \|y\|_2$
 $\|x\|_2 = \|y\|_2$

$$P = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \dots & \dots & a_{nn} \end{bmatrix}$$

$$= \begin{bmatrix} * \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Thm: If $x \in \mathbb{R}^n$, $y \in \mathbb{R}^n$, $\|x\|_2 = \|y\|_2$, then we can find a Householder matrix P (or W) $P^T P = I$ such that

$$Px = y$$

$$P \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix} = \begin{bmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$W = \pm \frac{x-y}{\|x-y\|_2}$$

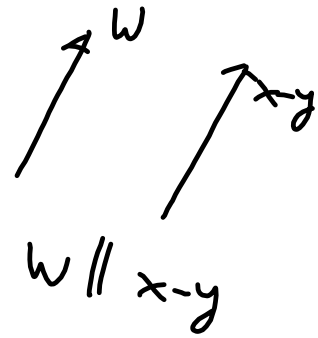
$$\alpha = \pm \|x\|_2 = \pm \sqrt{\sum_{i=1}^n a_{i1}^2}$$

Proof: $Px=y$, determine $w = \pm \frac{x-y}{\|x-y\|_2}$

$$(I - 2ww^T)x = y$$

$$x - 2w \underbrace{w^T x}_{\text{vector}} = y$$

$$\underline{x-y} = \underline{(2w^T x)} \underline{w}$$



$$w = \alpha(x-y) = \pm \frac{x-y}{\|x-y\|_2}$$

Verify, $w = \frac{x-y}{\|x-y\|_2}$

$$(I - 2ww^T)x \neq y$$

$$= x - 2ww^T x$$

$$= x - 2 \frac{(x-y)(x-y)^T}{(x-y)^T(x-y)} x \neq y$$

$$= y + (x-y) - \frac{2}{\dots}$$

$$= y + (x-y) \left(1 - \frac{2x^T x - 2x^T y}{(x-y)^T(x-y)} \right) = y$$

$$(x-y)^T(x-y) = \underbrace{x^T x}_{+^T x} - x^T y - y^T x + \underbrace{y^T y}_{+^T y}$$

$$= 2x^T x - 2x^T y$$

Ex: Find P such that $P^T = P^{-1}$

$$P \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix}^x = \begin{bmatrix} \alpha \\ 0 \\ 0 \end{bmatrix}^y$$

Step 1. Find α

$$\alpha = \pm 5$$

$$\sqrt{3^2 + 4^2} = \sqrt{\alpha^2}$$

Step 2 Find w

$$w = \frac{x-y}{\|x-y\|_2}$$

$$= \frac{\begin{bmatrix} 3-\alpha \\ 0 \\ 4 \end{bmatrix}}{\|x-y\|_2} \quad \alpha = -5 \text{ to avoid cancellation.}$$

$$y = \begin{bmatrix} \alpha \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -5 \\ 0 \\ 0 \end{bmatrix}$$

$$w = \begin{bmatrix} 3+5 \\ 0 \\ 4 \end{bmatrix} \frac{1}{\sqrt{80}} = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \frac{1}{\sqrt{5}}$$

$$P = I - 2ww^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{2}{5} \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1/5 & 0 & 2/5 \\ 0 & 1 & 0 \\ 2/5 & 0 & 3/5 \end{bmatrix}$$

$$I - 2ww^T$$

$$g_1^T g_3$$

$$P^T P = I$$

$$\frac{2}{5} \quad \frac{-1}{5}$$

QR decomposition of a matrix A

$$A \in \mathbb{R}^{n \times n}, \quad \det(A) \neq 0, \quad (\text{not essential condition})$$

We can find an orthogonal matrix Q

$$Q^T Q = I \quad \text{such that} \quad \begin{cases} Q^T A = R \\ A = QR \end{cases}$$

R is an upper triangular matrix

$$\|A\|_2 = \|R\|_2$$

Proof. Let $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \dots & \dots & a_{nn} \end{bmatrix}$

$$P_1 A = \begin{bmatrix} \tilde{a}_{11} & x & \dots \\ 0 & & \\ \vdots & & \\ 0 & & A_2 \end{bmatrix}$$

$$\tilde{a}_{11} = \sqrt{\sum_{i=1}^n a_{i1}^2}$$

$$w_1 = \frac{\begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix}}{\| \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix} \|}$$

$$P_2 = \begin{bmatrix} 1 & 0 \\ 0 & P_2 \end{bmatrix}$$

$$P_2 P_1 A = \begin{bmatrix} \tilde{a}_{11} & \dots & \dots \\ 0 & \tilde{a}_{22} & \dots \\ \vdots & \vdots & \ddots \\ 0 & \vdots & A_3 \end{bmatrix}$$

$$P_{n-1} P_{n-2} \dots P_1 A = R \quad \begin{bmatrix} x & x \\ x & x \end{bmatrix}$$

$$A = (P_{n-1} \dots P_1)^{-1} R$$

$$= P_1 P_2 \dots P_{n-1} R = QR$$

Discussions: Can we use QR
decomposition to solve $Ax=b$?

Yes. Worth it? $Ax=b$

pros. More accurate $QRx=b$

con's double's cost of $Rx=Q^T b$

LU.

backward
subst.

Destroy the structures,

$$P_1 A P_1^{-1} = \begin{bmatrix} \tilde{a}_{11} & & \\ 0 & & \\ \vdots & & \\ 0 & & \Lambda_2 \end{bmatrix} P_i = \begin{bmatrix} \tilde{a}_{11} \\ \tilde{a}_{21} \\ \vdots \\ \tilde{a}_{n1} \end{bmatrix}$$

Can we use QR to perform a similarity transform so that A becomes diagonal matrix. $Q^T A Q = D$

Thm: For any matrix $A \in \mathbb{C}^{n \times n}$, we can find the QR decomposition

$A = QR$, R is an upper triangular matrix. $Q^H Q = Q Q^H = I$.

$$A = LU \quad \rightarrow \quad PA = LU$$

$$Ax = b, \quad QRx = b$$

$$Rx = Q^H b$$

$$\|R\|_2 = \|A\|_2$$

QR needs more computation
destroy the structures of A . (double)

$$Q^T Q = I,$$

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$$\max_{1 \leq i, j \leq n} |g_{ij}| \leq 1$$

$$|a+bi| = \sqrt{a^2+b^2}$$

$$\sum_{j=1}^n g_{ij} \bar{g}_{ij} = \sum_{j=1}^n |g_{ij}|^2 = 1$$

$$|g_{i_0, j_0}|^2 \leq \sum_{j=1}^n |g_{ij}|^2 = 1$$

$$\begin{matrix} \langle & \langle^T \\ \Sigma & \Sigma^T = I \end{matrix}$$

Ex: $A = \begin{bmatrix} 0 & 1 & 0 \\ 3 & 0 & 25 \\ 4 & 5 & 0 \end{bmatrix}$

Find the QR decomposition.

unique e^{ik}

$$P_1 \begin{bmatrix} 0 \\ 3 \\ 4 \end{bmatrix}^x = \begin{bmatrix} \alpha \\ 0 \\ 0 \end{bmatrix}^y = \begin{bmatrix} \pm 5 \\ 0 \\ 0 \end{bmatrix}$$

$$0^2 + 3^2 + 4^2 = \alpha^2$$

$$25 = \alpha^2 \quad \alpha = \pm 5$$

$$W_1 = \frac{x-y}{\|x-y\|_2} = \begin{bmatrix} 5 \\ 3 \\ 4 \end{bmatrix} \frac{1}{\sqrt{25+9+16}}$$

$$P_1 A = [P_1 q_1, P_1 q_2, P_1 q_3]$$

$$= \begin{bmatrix} -5 & -4 & -15 \\ 0 & -3 & 16 \\ 0 & 1 & -12 \end{bmatrix}$$

$$P_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & I - 2W_2 W_2^T \\ 0 & & \end{bmatrix}$$

$$P_1 \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix}$$

$$= (I - 2W_1 W_1^T) \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix} - \frac{2}{5} \begin{bmatrix} 5 \\ 3 \\ 4 \end{bmatrix}$$

$$W_1^T \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix} = [5 \ 3 \ 4] \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix} = 25$$

$$P_1 \begin{bmatrix} 0 \\ 25 \\ 0 \end{bmatrix} = \left(I - \frac{2w_1 w_1^T}{50} \right) \begin{bmatrix} 0 \\ 25 \\ 0 \end{bmatrix}$$

$$P_1 a_3 = \begin{bmatrix} 0 \\ 25 \\ 0 \end{bmatrix} - \frac{1}{25} \begin{bmatrix} 5 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 5 & 3 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 25 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -15 \\ 16 \\ -12 \end{bmatrix}$$

$$P_2 P_1 A = P_2 \begin{bmatrix} -5 & -4 & -15 \\ 0 & -3 & 16 \\ 0 & 1 & -12 \end{bmatrix}$$

$$\tilde{P}_2 \begin{bmatrix} -3 \\ 1 \end{bmatrix} = \begin{bmatrix} \beta \\ 0 \end{bmatrix} = \begin{bmatrix} \pm\sqrt{10} \\ 0 \end{bmatrix} = \begin{bmatrix} -5 & -4 & -15 \\ 0 & \sqrt{10} & x \\ 0 & 0 & x \end{bmatrix}$$

$$w_2 = \frac{x-y}{\|x-y\|_2} = \begin{bmatrix} -3-\sqrt{10} \\ 1 \end{bmatrix} \frac{1}{\sqrt{(3+\sqrt{10})^2 + 1}} = R \quad \underline{w_2^T}$$

QR method for algebraic eigenvalue problems: find all eigenvalues.

Start with $A_0 = A, \quad A \in \mathbb{R}^{n \times n}$

$$A_0 = Q_0 R_0, \quad Q_0^H Q_0 = I, \quad R_0 \text{ is an upper tri.}$$

$$A_1 = R_0 Q_0$$

$$A_1 = Q_1 R_1, \quad Q_1^H Q_1 = I, \quad R_1 \text{ is upper}$$

$$A_2 = R_1 Q_1$$

...

QR method

$$\begin{cases} A_k = Q_k R_k \\ A_{k+1} = R_k Q_k \end{cases} \quad Q_k^H Q_k = I, \quad R_k \text{ upper tri.}$$

$k=0, 1, \dots$, until converge

Thm. From the QR method, we have

If $A \in \mathbb{R}^{n \times n}$, $|\lambda_{k1}| > |\lambda_{k2}| > \dots > |\lambda_{kn}|$

(i) $A_{k+1} \sim A_k \sim A$

$$\frac{S^H A_{k+1} S}{S^H A_k S} = A_k$$

$|\lambda_{k1}|$ if λ_{k1} is real.
 $|\overline{\lambda_{k2}}|$ if λ_{k1} and λ_{k2} is a complex pair.

$A_{k+1}, A_k,$ and A all have the same eigenvalues.

$$(ii) \lim_{k \rightarrow \infty} A_k = R_A = \begin{bmatrix} R_{11} & R_{12} & \dots & R_{1s} \\ & R_{22} & & \vdots \\ & & \ddots & \\ 0 & & & R_{ss} \end{bmatrix}$$

a block upper triangular matrix

Where R_{kk} is either a 1 by 1
or 2 by 2 matrix

corresponding to either a simple
or complex eigenvalue pair.

$$\det(\lambda I - A) = \prod \det(\lambda_k I - R_{kk}) = 0$$

Schur form of A

QR method $A_0 = A \in \mathbb{R}^{n \times n}$.

$$A_0 = Q_0 R_0$$

$$A_1 = R_0 Q_0$$

$$\begin{cases} A_k = Q_k R_k \\ A_{k+1} = R_k Q_k \end{cases} \rightarrow \begin{aligned} & Q_k^T A_k Q_k \\ &= \underline{Q_k^T Q_k} \underline{R_k Q_k} \\ &= I A_{k+1} \end{aligned}$$

$$A_{k+1} \sim A_k \sim A_{k-1} \dots = A_0 = A = A_{k+1}$$

$$A_k \rightarrow \begin{bmatrix} R_{11} & R_{12} & & R_{1s} \\ & R_{22} & & \vdots \\ & & \ddots & \vdots \\ 0 & & & R_{ss} \end{bmatrix} \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

$$\begin{bmatrix} \lambda_k \\ \lambda_{k-1} \end{bmatrix}$$

$$\begin{bmatrix} \lambda_i & & & 0 \\ & \ddots & & \vdots \\ & & \ddots & \vdots \\ 0 & & & \lambda_i \end{bmatrix}$$

Shifted QR method $A = A_0$

for $k=0, 1, \dots$ until converges

$$\begin{cases} A_k - \sigma_k I = Q_k R_k \\ A_{k+1} = R_k Q_k + \sigma_k I \end{cases}$$

end

Stop criteria:

$$\max_{\substack{3 \leq i \leq n \\ 1 \leq j \leq i+2 \leq n}} |a_{ij}| < \text{tol}$$

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QR method is expensive.

each iteration $A_k = Q_k R_k$ $O(\frac{2}{3}n^3)$
 $A_{k+1} = R_k Q_k$ $O(\frac{1}{2}n^3)$

Can we use QR method to reduce A to a diagonal matrix? In finite operations

$A \xrightarrow{\text{similarity transform}} D$ No if A is not diagonalizable, e.g. Jordan Block

- 1. $A = A^T, A = A^H$
- 2. A has complete eigenvectors

We can use similarity transform to reduce A to an upper Hessenberg matrix.

$$H = \begin{bmatrix} x & x & x & \dots & x \\ x & x & x & x & \dots \\ 0 & x & & & \\ \vdots & \vdots & & & \\ 0 & \vdots & & & \end{bmatrix}$$

in $n-2$ transforms.

If $A = A^T$, we can transform A to a tridiagonal matrix.

Step 1. $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & \ddots & \\ a_{n1} & & & a_{nn} \end{bmatrix} \quad n \geq 2$

$$P_1 A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \tilde{a}_{21} & & & \\ \vdots & & A_2 & \\ 0 & & & \end{bmatrix}$$

$$P_1 = \begin{bmatrix} 1 & & \dots & 0 \\ & \ddots & & \\ & & I_{n-1} - \frac{2w_1 w_1^T}{|w_1|^2} & \\ & & & \end{bmatrix}$$

$$w_1 = \begin{pmatrix} a_{12} \pm \tilde{a}_{21} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix} \quad \left\| \begin{array}{l} \tilde{a}_{21} \\ \vdots \\ \tilde{a}_{n1} \end{array} \right\| \parallel \parallel$$

$$|\tilde{a}_{21}| = \pm \sqrt{\sum_{i=2}^n |a_{i1}|^2}$$

$$\tilde{a}_{21} = -\text{sgn}(a_{21}) \sqrt{\sum_{i=2}^n |a_{i1}|^2}$$

$$P_1 A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \hat{a}_{21} & \hat{a}_{22} & \dots & \hat{a}_{2n} \\ 0 & \hat{a}_{32} & & \\ \vdots & \vdots & & \\ 0 & \hat{a}_{n2} & & \hat{a}_{nn} \end{bmatrix} \quad \begin{matrix} \hat{P}_1 A \\ \begin{bmatrix} \hat{a}_{11} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \end{matrix} \hat{P}_1$$

$$P_1 A P_1 = \begin{bmatrix} a_{11} \\ \hat{a}_{21} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \times \begin{bmatrix} \hat{a}_{11} \\ \vdots \\ x \end{bmatrix}$$

$$P_1 = P_1^T = P_1^{-1}$$

Similarity transform.

$$P_{n-2} \dots P_2 P_1 A P_1 P_2 \dots P_{n-2}$$

In finite number of operations.

$$P A P^T = H.$$

If A is symmetric $A = A^T$

$$(P A P^T)^T = H^T$$

$$P A^T P^T = P A P^T = H^T \Rightarrow H^T = H$$

$$H = \begin{bmatrix} a_{11} & a_{21} & 0 & 0 & \dots & 0 \\ a_{21} & a_{22} & a_{32} & 0 & \dots & 0 \\ 0 & a_{32} & a_{33} & & & \\ \vdots & & & & & \\ 0 & 0 & & & & \\ & & & & & a_{n,n-1} \\ & & & & & a_{n,n-1} & a_{nn} \end{bmatrix}$$

Then we apply the QR method.

QR method for upper Hessenberg matrix.

$$Q_1 H = \begin{bmatrix} h_{11} & h_{12} & \dots & h_{1n} \\ h_{21} & h_{22} & \dots & \\ 0 & \diagdown & & \\ \vdots & & \diagdown & \\ & & & h_{nn} \end{bmatrix}$$

Given's notation
 $\rightarrow h_{21} \rightarrow 0$.

divide - congruent



Givens' matrix.

$$Q = \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix}$$

$$Q^T Q = I \quad \begin{matrix} g_{21}^2 + g_{11}^2 = 1 \\ g_{12}^2 + g_{22}^2 = 1 \end{matrix}$$

$$= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$g_{11}g_{12} + g_{21}g_{22} = 0$$

$$|g_{ij}| \leq 1 \text{ for all } i, j$$

Ex: $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$

$$P_1 = I - \frac{2w_1w_1^T}{\|w_1\|_2^2}$$

$$QA = \begin{bmatrix} * & * \\ 0 & * \end{bmatrix} \quad \pm\sqrt{2^2+1} = x$$

$$Q = \begin{pmatrix} e^{i\alpha_1} & \\ & e^{i\alpha_2} \end{pmatrix} P_1$$

Real: $\begin{bmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{bmatrix} P_1$ real.

$$= \begin{bmatrix} \pm\sqrt{5} & * \\ 0 & x \end{bmatrix}$$

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} \pm\sqrt{5} & * \\ 0 & * \end{bmatrix}$$

$$-2\sin \theta + \cos \theta = 0$$

$$\tan \theta = \frac{1}{2}$$

$$1 + \tan^2 \theta = \frac{1}{\cos^2 \theta}$$

$$1 + \left(\frac{1}{2}\right)^2 = \frac{1}{\cos^2 \theta}$$

$$\cos \theta = \pm \frac{2}{\sqrt{5}} = \frac{2}{\sqrt{5}} \text{ take}$$

Take:

$$\sin \theta = \pm \sqrt{1 - \cos^2 \theta} = \pm \frac{1}{\sqrt{5}}$$

$$\cos \theta = \frac{2}{\sqrt{5}}$$

$$\sin \theta = \frac{1}{\sqrt{5}}$$

$$\text{verify: } \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} \sqrt{5} & \frac{2}{\sqrt{5}} \\ 0 & \frac{3}{\sqrt{5}} \end{bmatrix}$$

If we want to reduce one entry to zero, then we should use the Givens' rotation.

A. Want to find all eigenvalues, we can use the QR method. It's computationally expensive. Often we prefer

$A \xrightarrow[\text{transform}]{\text{Householder}}$ H the upper Hessenberg form.
Need $n-2$ steps.

Then we apply Givens' rotations for the QR method.

QR

$$A_1 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{G_{12}} \begin{bmatrix} 2 & 2 & 2 & 2 \\ 0 & 2 & 2 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$G_{2j} = \begin{bmatrix} & & & & \\ & \dots & & & \\ & \cos\theta & & & s\cdot 0 \\ & & \dots & & \\ s\cdot 0 & & & \dots & \\ & & & & \cos\theta \end{bmatrix} \xrightarrow{G_{23}} \begin{bmatrix} 2 & 2 & 2 & 2 \\ 0 & 3 & 3 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\xrightarrow{G_{34}} \begin{bmatrix} 2 & 2 & 2 & 2 \\ 0 & 3 & 3 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & 0 & 4 \end{bmatrix} = R$$

To transfer H to an upper triangular matrix using Givens' rotation requires $O(n^2)$ operations.

- Generalized ^{algebraic} eigenvalue problems

$$Ax = \lambda Bx \rightarrow A'x = \lambda x$$

- Perturbation Theory $A \quad A+E$

$$\|E\| \leq c \|A\|$$

$$Ax = \lambda x \quad (A+E)\bar{x} = \bar{\lambda}\bar{x}$$

J. H. Wilkinson's backward error analysis.

Thm If A is diagonalizable, (A has completed eigenvectors), all Jordan blocks are 1 by 1.

We can find S , $\det(S) \neq 0$, such that

$$S^{-1}AS = D$$

$$A \sim \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix}$$

$$A+E$$

$$=$$

$$\min |\lambda_i - \bar{\lambda}_i| \leq \underbrace{\text{cond}(S)}_{=1} \|E\|$$

$$\begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{pmatrix}$$

$$S^{-1} = S^T$$

If $AA^T = A^T A$, A is called a normal matrix, then $\text{cond}(S) = 1$.

If $A = A^T$, then is a normal matrix!