

Stokes Equations

$$\begin{cases} \nabla p = \mu \Delta \vec{u} + \vec{F} \\ \nabla \cdot \vec{u} = 0 \\ \vec{u}|_{\partial\Omega} = 0 \end{cases} \quad (x, y) \in \Omega$$

Reynolds number is very small, inertia term is neglected, very viscous, small velocity. Creeping flow.

Finite element method: A eliminate p .

$$\int_{\Omega} \nabla p \cdot \vec{v} \, dx dy = \iint_{\Omega} \mu \Delta \vec{u} \cdot \vec{v} \, dx dy + \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx dy$$

Require

$$\begin{cases} \nabla \cdot \vec{u} = 0 \\ \vec{v}|_{\partial\Omega} = 0 \end{cases} \quad \text{tough constraints.}$$

$$\vec{u} = (u_1, u_2)$$

$$\nabla \vec{u} = \begin{bmatrix} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial y} \\ \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial y} \end{bmatrix}$$

$$\Rightarrow \int_{\partial\Omega} (\nabla p \cdot \vec{n}) \vec{v} \, dx dy - \iint_{\Omega} p \nabla \cdot \vec{v} \, dx dy$$

$$= - \iint_{\Omega} \mu (\nabla \vec{u} \cdot \nabla \vec{v}) \, dx dy + \int_{\partial\Omega} \mu \vec{u} \cdot \vec{v} + \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx dy$$

$$\Rightarrow \mu \iint_{\Omega} \left\{ (\nabla u_1 \cdot \nabla v_1) + (\nabla u_2 \cdot \nabla v_2) \right\} \, dx dy = \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx dy$$

$$V = \left\{ \vec{v} \in [H_0^1(\Omega)]^2, \nabla \cdot \vec{u} = 0, \vec{v}|_{\partial\Omega} = 0 \right\}$$

Difficulty: How to find V space,
Use the stream function $\phi(x, y)$

$$\vec{v} = \text{rot } \phi = \left\langle \frac{\partial \phi}{\partial y}, -\frac{\partial \phi}{\partial x} \right\rangle$$

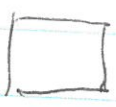
then $\nabla \cdot \vec{v} = \text{div } \vec{v} = \frac{\partial^2 \varphi}{\partial x^2 \partial y} - \frac{\partial^2 \varphi}{\partial y^2 \partial x} = 0$

Let W_h be a finite dimensional subspace of $H_0^2(\Omega) = \{ \vec{v}(x), \vec{v}(x)|_{\partial\Omega} = 0, \vec{v}(x) \in H^2(\Omega) \}$

Then $V_h = \{ \vec{v}, \vec{v} = \begin{bmatrix} \frac{\partial \varphi}{\partial y} \\ -\frac{\partial \varphi}{\partial x} \end{bmatrix}, \vec{v}|_{\partial\Omega} = 0, \varphi \in W_h \}$

Error estimate

$\| \vec{u} - \vec{u}_h \|_{H^1(\Omega)} \leq C h^4 \| \vec{u} \|_{H^5(\Omega)}$
 $W_h = \{ \varphi(x, y), \frac{\partial \varphi}{\partial x}|_{\partial\Omega} = 0, \frac{\partial \varphi}{\partial y}|_{\partial\Omega} = 0, \varphi \in P_5(\Omega), \varphi \in C^1(\Omega) \cap H^2(\Omega) \}$
 Note that: If the boundary is periodic for all variables,

 $\vec{u}(a, y) = \vec{u}(b, y), \vec{u}(x, c) = \vec{u}(x, d)$
 $p(a, y) = p(b, y), p(x, c) = p(x, d)$

then we have

$$\Delta p = \nabla \cdot \mu \overset{=0}{\Delta \vec{u}} + \nabla \cdot \vec{F}$$

$$\Rightarrow \begin{cases} \Delta p = \nabla \cdot \vec{F} \\ \mu \Delta u_1 = p_x + F_x \\ \mu \Delta u_2 = p_y + F_y \end{cases}$$

Method Mixed finite element method
 Do not impose the incompressibility condition for \vec{v} .

$$\begin{aligned}
\iint_{\Omega} \nabla p \cdot \vec{v} \, dx \, dy &= \iint_{\Omega} \mu \nabla \cdot \vec{u} \cdot \vec{v} + \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx \, dy \\
+ \int_{\partial \Omega} p \vec{n} \cdot \vec{v} \, ds - \iint_{\Omega} p \nabla \cdot \vec{v} \, dx \, dy \\
&= \int_{\partial \Omega} \mu \nabla \vec{u} \cdot \nu \, ds - \iint_{\Omega} \nabla \vec{u} \cdot \nabla \vec{v} \, dx \, dy + \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx \, dy \\
\Rightarrow \iint_{\Omega} \nabla \vec{u} \cdot \nabla \vec{v} \, dx \, dy - \iint_{\Omega} p \nabla \cdot \vec{v} \, dx \, dy &= \iint_{\Omega} \vec{F} \cdot \vec{v} \, dx \, dy
\end{aligned}$$

$$\begin{aligned}
\text{or } (\nabla \vec{u}, \nabla \vec{v}) - (p, \operatorname{div} \vec{v}) &= (\vec{F}, \vec{v}) \\
(\nabla w, \nabla v) &= \sum_{i=1}^2 \int_{\Omega} (\nabla w_i \cdot \nabla v_i) \, dx \, dy
\end{aligned}$$

second equation

$$\begin{aligned}
\nabla \cdot \vec{u} &= 0, \quad \operatorname{div} \vec{u} = 0 \\
\iint_{\Omega} (q \cdot \operatorname{div} \vec{u}) \, dx \, dy &= 0
\end{aligned}$$

Impose additional equation for the pressure

$$\begin{aligned}
\iint_{\Omega} p \, dx \, dy &= 0 \\
\text{or } p(x^*, y^*) &= p_0 \quad \text{fixed at one point}
\end{aligned}$$

$$V = \{ \vec{v} \in [H^1(\Omega)]^2, \vec{v}|_{\partial \Omega} = 0 \}$$

$$H = \{ q \in L_2(\Omega), \iint_{\Omega} q \, dx \, dy = 0 \}$$

Different sub-spaces, so it is called a mixed finite elements.

Stability requirement,

$$\|u_h\|_{H^1(\Omega)} + \|p_h\|_{L^2(\Omega)} \leq C \underbrace{\sup_{v \in H^1(\Omega)} \frac{(f, v)_{L^2(\Omega)}}{\|v\|_{H^1(\Omega)}}}_{\|f\|_{H^1(\Omega)}}$$

Then we have

$$\|u_h\|_{H^1(\Omega)}^2 \leq (f, u_h) \leq \|f\|_{H^1(\Omega)} \|u_h\|_{H^1(\Omega)}$$

$$\text{or } \|u_h\|_{H^1(\Omega)} \leq \|f\|_{H^1(\Omega)}$$

Numerics: $V_h = \{ \vec{v} \in V : \vec{v}|_K \in [\mathcal{Q}_2(K)]^2, \forall K \in \mathcal{T}_h, \vec{v}|_{\partial\Omega} = 0 \}$
 $M_h = \{ \xi \in M : \xi|_K \in \mathcal{Q}_0(K), \forall K \in \mathcal{T}_h \}$

or $V_h = \{ \vec{v} \in V : \vec{v}|_K \in [\mathcal{Q}_1(K)]^2, \forall K \in \mathcal{T}_h \}$
 $M_h = \{ \xi \in M : \xi|_K \in \mathcal{Q}_0(K), \forall K \in \mathcal{T}_h \}$

or

Saddle problem

$$V_h \in \{ \vec{v} \in V; \vec{v}|_K \in [\mathcal{P}_2(K)]^2, \forall K \in \mathcal{T}_h \}$$

$$M_h \in \{ \xi \in M, \xi|_K \in \mathcal{P}_1(K), \forall K \in \mathcal{T}_h \}$$

Reference: Numerical solution of PDE by the finite element method

Claes Johnson.

Cambridge University Press, 1998

Another method,

Least squares finite element method

Eigenvalue Problem.

$$\begin{cases} -u'' + 0.5u = 0 \\ u(0) = 0, u(\pi) = 0 \end{cases}$$

Does it exist?

$$\begin{cases} -(pu')' + qu - \lambda u = 0 & a < x < b \\ u(a) = \alpha, \quad \alpha u(b) + \beta u'(b) = 0 \end{cases}$$

Weak form $\int (pu'v' + (q - \lambda)uv) dx + \frac{\alpha}{\beta} p(b)u(b)v(b) = \int fv dx + \frac{\gamma}{\beta} p(b)v(b)$

$a(u, u) \geq \alpha \|u\|_2^2$ is not true. The solution may not exist or be unique. For example, $-u'' + \lambda u = 0$ for $0 \leq x < \pi$ with $u(0) = 0$ and $u(\pi) = 0$. $u(x) = \sin x$ or $u = 0$ is a solution. trivial solution

For certain λ , there ~~are~~ is another non-trivial solution. Such λ is called an eigenvalue of the Sturm-Liouville problem. The non-trivial solution is called the eigenvector.

$$\lambda_1, \lambda_2, \dots, \lambda_n, \dots \quad \text{infinite dimensions.}$$

$$u_1, u_2, \dots, u_n, \dots \quad u_i \neq 0$$

They form a basis for the ~~solution~~ Sturm-Liouville problem.

The solution $\begin{cases} -(pu')' + qu = f \\ u(a) = u_a, \quad \alpha u(b) + \beta u'(b) = 0 \end{cases}$

can be expressed in terms of u_i :

$$u(x) = \sum_{j=1}^{\infty} \alpha_j u_j(x)$$

$$\begin{aligned} -u'' &= f \\ u(0) &= 0, \quad u(\pi) = 0 \end{aligned}$$

$$u(x) = \sum_{j=1}^{\infty} \alpha_j \sin jx$$

$$-u'' + \lambda u = 0$$

$$a(u, v) = \int (\rho u'v' + f_{uv}) dx + \frac{1}{\beta} p(b) u(b)v(b)$$

Numerics.

$$\begin{bmatrix} a(\varphi_1, \varphi_1) & \dots & a(\varphi_1, \varphi_n) \\ \vdots & \ddots & \vdots \\ a(\varphi_n, \varphi_1) & \dots & a(\varphi_n, \varphi_n) \end{bmatrix} U - \lambda \begin{bmatrix} (\varphi_1, \varphi_1) & (\varphi_1, \varphi_2) & \dots & 0 \\ (\varphi_2, \varphi_1) & (\varphi_2, \varphi_2) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & (\varphi_n, \varphi_n) \end{bmatrix} U = 0$$

$$A^W - \lambda B^W = 0$$

Generalized eigenvalue problem.

$$[V, D] = \text{eig}(A, B);$$

| eigenvalues
eigenvectors.

$$u(x) = \sum_{j=1}^n \alpha_j \varphi_j(x).$$

Theorem: Let $u(x) \in C^2[a, b]$ be the exact solution of $-u''(x) = f(x)$, $u(a) = u(b) = 0$. $u_h(x)$ be the FEM solution using the hat basis function over a given triangulation. Then

- (1) $\|u - u_h\|_{\infty} = \max_{a \leq x \leq b} |u(x) - u_h(x)| \leq h^2 \|u''\|_{\infty} / 8$
 (2) $u_h(x_j) = u(x_j)$, $j = 0, 1, \dots, M$.

Proof: Define $a(u, v) = \int_a^b u'v' dx$. Let V_h be the finite dimensional space generated by the hat basis functions; u_I is the interpolation function of $u(x)$. For any $v_h(x) \in V_h$, we have

$$\int_{x_i}^{x_{i+1}} (u - u_I)' v_h' dx = v_h'(u - u_I) \Big|_{x_i}^{x_{i+1}} - \int_{x_i}^{x_{i+1}} (u - u_I) v_h'' dx = 0$$

since $u(x_j) = u_I(x_j)$, $j = 0, 1, \dots, M$. $v_h''(x) \equiv 0$ in (x_i, x_{i+1}) .

Thus

$$a(u - u_I, v_h) = \int_a^b (u - u_I)' v_h' dx = \sum_{i=0}^{M-1} \int_{x_i}^{x_{i+1}} (u - u_I)' v_h' dx = 0$$

We also know that

$$a(u - u_h, v_h) = 0, \text{ for any } v_h \in V_h$$

Subtract to get

$$a(u - u_I - u + u_h, v_h) = 0$$

That is $a(u_h - u_I, v_h) = 0$ for any $v_h \in V_h$

Take $v_h = u_h - u_I$, we have

$$a(u_h - u_I, v_h - u_I) = 0$$