

Cylindrical co-ordinates

To the co-ordinates $\xi_1 = x$, $\xi_2 = \sigma$, $\xi_3 = \phi$ (where ϕ is the azimuthal angle about the axis $\sigma = 0$) there correspond the scale factors

$$h_1 = 1, \quad h_2 = 1, \quad h_3 = \sigma.$$

$$\text{Then} \quad \frac{\partial \mathbf{a}}{\partial \phi} = \mathbf{0}, \quad \frac{\partial \mathbf{b}}{\partial \phi} = \mathbf{c}, \quad \frac{\partial \mathbf{c}}{\partial \phi} = -\mathbf{b},$$

and \mathbf{a} , \mathbf{b} , \mathbf{c} are independent of x and σ .

$$\nabla V = \mathbf{a} \frac{\partial V}{\partial x} + \mathbf{b} \frac{\partial V}{\partial \sigma} + \frac{\mathbf{c}}{\sigma} \frac{\partial V}{\partial \phi},$$

$$\mathbf{n} \cdot \nabla \mathbf{F} = \mathbf{a} (\mathbf{n} \cdot \nabla F_x) + \mathbf{b} \left(\mathbf{n} \cdot \nabla F_\sigma - \frac{n_\phi F_\phi}{\sigma} \right) + \mathbf{c} \left(\mathbf{n} \cdot \nabla F_\phi + \frac{n_\sigma F_\sigma}{\sigma} \right),$$

$$\nabla \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{1}{\sigma} \frac{\partial (\sigma F_\sigma)}{\partial \sigma} + \frac{1}{\sigma} \frac{\partial F_\phi}{\partial \phi},$$

$$\nabla \times \mathbf{F} = \mathbf{a} \left\{ \frac{1}{\sigma} \frac{\partial (\sigma F_\phi)}{\partial \sigma} - \frac{1}{\sigma} \frac{\partial F_\sigma}{\partial \phi} \right\} + \mathbf{b} \left\{ \frac{1}{\sigma} \frac{\partial F_x}{\partial \phi} - \frac{\partial F_\phi}{\partial x} \right\} + \mathbf{c} \left\{ \frac{\partial F_\sigma}{\partial x} - \frac{\partial F_x}{\partial \sigma} \right\},$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{1}{\sigma} \frac{\partial}{\partial \sigma} \left(\sigma \frac{\partial V}{\partial \sigma} \right) + \frac{1}{\sigma^2} \frac{\partial^2 V}{\partial \phi^2},$$

$$\nabla^2 \mathbf{F} = \mathbf{a} (\nabla^2 F_x) + \mathbf{b} \left(\nabla^2 F_\sigma - \frac{F_\sigma}{\sigma^2} - \frac{2}{\sigma^2} \frac{\partial F_\phi}{\partial \phi} \right) + \mathbf{c} \left(\nabla^2 F_\phi + \frac{2}{\sigma^2} \frac{\partial F_\sigma}{\partial \phi} - \frac{F_\phi}{\sigma^2} \right).$$

Rate-of-strain tensor:

$$e_{xx} = \frac{\partial u_x}{\partial x}, \quad e_{\sigma\sigma} = \frac{\partial u_\sigma}{\partial \sigma}, \quad e_{\phi\phi} = \frac{1}{\sigma} \frac{\partial u_\phi}{\partial \phi} + \frac{u_\sigma}{\sigma},$$

$$e_{\sigma\phi} = \frac{\sigma}{2} \frac{\partial}{\partial \sigma} \left(\frac{u_\phi}{\sigma} \right) + \frac{1}{2\sigma} \frac{\partial u_\sigma}{\partial \phi}, \quad e_{\phi\sigma} = \frac{1}{2\sigma} \frac{\partial u_x}{\partial \phi} + \frac{1}{2} \frac{\partial u_\phi}{\partial x}, \quad e_{x\sigma} = \frac{1}{2} \frac{\partial u_\sigma}{\partial x} + \frac{1}{2} \frac{\partial u_x}{\partial \sigma}.$$

Equation of motion for an incompressible fluid, with no body force:

$$\frac{\partial u_x}{\partial t} + \mathbf{u} \cdot \nabla u_x = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^2 u_x,$$

$$\frac{\partial u_\sigma}{\partial t} + \mathbf{u} \cdot \nabla u_\sigma - \frac{u_\sigma^3}{\sigma} = -\frac{1}{\rho} \frac{\partial p}{\partial \sigma} + \nu \left(\nabla^2 u_\sigma - \frac{u_\sigma}{\sigma^2} - \frac{2}{\sigma^2} \frac{\partial u_\phi}{\partial \phi} \right),$$

$$\frac{\partial u_\phi}{\partial t} + \mathbf{u} \cdot \nabla u_\phi + \frac{u_\sigma u_\phi}{\sigma} = -\frac{1}{\rho\sigma} \frac{\partial p}{\partial \phi} + \nu \left(\nabla^2 u_\phi + \frac{2}{\sigma^2} \frac{\partial u_\sigma}{\partial \phi} - \frac{u_\phi}{\sigma^2} \right).$$

Polar co-ordinates in two dimensions

The relevant formulae can be obtained from those for the above cylindrical co-ordinates by suppressing all components and derivatives in the direction

of the x -co-ordinate line, but are written out here in view of the frequency of their use. The co-ordinates are

$$\xi_1 = r, \quad \xi_2 = \theta, \quad \text{and} \quad h_1 = 1, \quad h_2 = r,$$

$$\frac{\partial \mathbf{a}}{\partial r} = \mathbf{0}, \quad \frac{\partial \mathbf{a}}{\partial \theta} = \mathbf{b}, \quad \frac{\partial \mathbf{b}}{\partial r} = \mathbf{0}, \quad \frac{\partial \mathbf{b}}{\partial \theta} = -\mathbf{a}.$$

$$\nabla V = \mathbf{a} \frac{\partial V}{\partial r} + \frac{\mathbf{b}}{r} \frac{\partial V}{\partial \theta},$$

$$\mathbf{n} \cdot \nabla \mathbf{F} = \mathbf{a} \left(\mathbf{n} \cdot \nabla F_r - \frac{n_\theta F_\theta}{r} \right) + \mathbf{b} \left(\mathbf{n} \cdot \nabla F_\theta + \frac{n_r F_r}{r} \right),$$

$$\nabla \cdot \mathbf{F} = \frac{1}{r} \frac{\partial (r F_r)}{\partial r} + \frac{1}{r} \frac{\partial F_\theta}{\partial \theta},$$

$$\nabla \times \mathbf{F} = \left\{ \frac{1}{r} \frac{\partial (r F_\theta)}{\partial r} - \frac{1}{r} \frac{\partial F_r}{\partial \theta} \right\} \mathbf{a} \times \mathbf{b},$$

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \theta^2},$$

$$\nabla^2 \mathbf{F} = \mathbf{a} \left(\nabla^2 F_r - \frac{F_r}{r^2} - \frac{2}{r^2} \frac{\partial F_\theta}{\partial \theta} \right) + \mathbf{b} \left(\nabla^2 F_\theta + \frac{2}{r^2} \frac{\partial F_r}{\partial \theta} - \frac{F_\theta}{r^2} \right).$$

Rate-of-strain tensor:

$$e_{rr} = \frac{\partial u_r}{\partial r}, \quad e_{\theta\theta} = \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r}, \quad e_{r\theta} = \frac{r}{2} \frac{\partial}{\partial r} \left(\frac{u_\theta}{r} \right) + \frac{1}{2r} \frac{\partial u_r}{\partial \theta}.$$

Equation of motion for an incompressible fluid, with no body force:

$$\frac{\partial u_r}{\partial t} + \left(u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} \right) u_r - \frac{u_\theta^2}{r} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\nabla^2 u_r - \frac{u_r}{r^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} \right),$$

$$\frac{\partial u_\theta}{\partial t} + \left(u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} \right) u_\theta + \frac{u_r u_\theta}{r} = -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left(\nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2} \right).$$

when finding the components of $\nabla^2 \mathbf{F}$ in a particular co-ordinate system, to use the identity $\nabla^2 \mathbf{F} = \nabla(\nabla \cdot \mathbf{F}) - \nabla \times (\nabla \times \mathbf{F})$

and the above expressions for grad, div and curl.

Consider now the components of the rate-of-strain tensor expressed in terms of velocity components and derivatives relative to the curvilinear system. The gradient, in the direction \mathbf{n} , of the component of velocity \mathbf{u} in the fixed direction \mathbf{m} is

$$\mathbf{n} \cdot \nabla(\mathbf{m} \cdot \mathbf{u}), = \mathbf{m} \cdot (\mathbf{n} \cdot \nabla \mathbf{u}).$$

Diagonal elements of the rate-of-strain tensor represent rates of extension, obtained by putting $\mathbf{m} = \mathbf{n}$, and the non-diagonal elements involve velocity gradients for which \mathbf{m} and \mathbf{n} are orthogonal. We see then, from the above formula for $\mathbf{n} \cdot \nabla \mathbf{F}$, that the components of the rate-of-strain tensor relative to Cartesian axes locally parallel to \mathbf{a} , \mathbf{b} and \mathbf{c} (to which the suffixes 1, 2, 3 refer, respectively) are

$$e_{11} = \mathbf{a} \cdot (\mathbf{a} \cdot \nabla \mathbf{u}) = \frac{1}{h_1} \frac{\partial u_1}{\partial \xi_1} + \frac{u_2}{h_1 h_2} \frac{\partial h_1}{\partial \xi_2} + \frac{u_3}{h_3 h_1} \frac{\partial h_1}{\partial \xi_3},$$

$$e_{23} = \frac{1}{2} \mathbf{b} \cdot (\mathbf{c} \cdot \nabla \mathbf{u}) + \frac{1}{2} \mathbf{c} \cdot (\mathbf{b} \cdot \nabla \mathbf{u}) = \frac{h_3}{2h_2} \frac{\partial}{\partial \xi_2} \left(\frac{u_3}{h_3} \right) + \frac{h_2}{2h_3} \frac{\partial}{\partial \xi_3} \left(\frac{u_2}{h_2} \right),$$

with four other expressions obtained by cyclic interchange of suffixes. The components of the stress tensor σ_{ij} can be obtained from those of rate of strain, using the relation (for an incompressible fluid)

$$\sigma_{ij} = -p \delta_{ij} + 2\mu e_{ij}.$$

The components of all terms in the equation of motion of a fluid in the directions \mathbf{a} , \mathbf{b} , \mathbf{c} may now be found by simple substitution in the appropriate expressions above. The components of the term $\mathbf{u} \cdot \nabla \mathbf{u}$ in the acceleration are obtained from the expression for $\mathbf{n} \cdot \nabla \mathbf{F}$.

Applications to some particular co-ordinate systems are as follows.

Spherical polar co-ordinates

To the co-ordinates $\xi_1 = r$, $\xi_2 = \theta$, $\xi_3 = \phi$ (where ϕ is the azimuthal angle about the axis $\theta = 0$) there correspond the scale factors

$$h_1 = 1, \quad h_2 = r, \quad h_3 = r \sin \theta. \quad \begin{matrix} 0 \leq \phi \leq 2\pi \\ 0 \leq \theta \leq \pi \end{matrix}$$

Then

$$\frac{\partial \mathbf{a}}{\partial r} = 0, \quad \frac{\partial \mathbf{a}}{\partial \theta} = \mathbf{b}, \quad \frac{\partial \mathbf{a}}{\partial \phi} = \sin \theta \mathbf{c},$$

$$\frac{\partial \mathbf{b}}{\partial r} = 0, \quad \frac{\partial \mathbf{b}}{\partial \theta} = -\mathbf{a}, \quad \frac{\partial \mathbf{b}}{\partial \phi} = \cos \theta \mathbf{c},$$

$$\frac{\partial \mathbf{c}}{\partial r} = 0, \quad \frac{\partial \mathbf{c}}{\partial \theta} = 0, \quad \frac{\partial \mathbf{c}}{\partial \phi} = -\sin \theta \mathbf{a} - \cos \theta \mathbf{b}.$$

$$\nabla V = \mathbf{a} \frac{\partial V}{\partial r} + \frac{\mathbf{b}}{r} \frac{\partial V}{\partial \theta} + \frac{\mathbf{c}}{r \sin \theta} \frac{\partial V}{\partial \phi},$$

$$\mathbf{n} \cdot \nabla \mathbf{F} = \mathbf{a} \left(\mathbf{n} \cdot \nabla F_r - \frac{n_\theta F_\theta}{r} - \frac{n_\phi F_\phi}{r} \right) + \mathbf{b} \left(\mathbf{n} \cdot \nabla F_\theta - \frac{n_\phi F_\phi}{r} \cot \theta + \frac{n_\theta F_r}{r} \right) + \mathbf{c} \left(\mathbf{n} \cdot \nabla F_\phi + \frac{n_\theta F_r}{r} + \frac{n_\phi F_\theta}{r} \cot \theta \right),$$

$$\nabla \cdot \mathbf{F} = \frac{1}{r^2} \frac{\partial(r^2 F_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\sin \theta F_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial F_\phi}{\partial \phi},$$

$$\nabla \times \mathbf{F} = \frac{\mathbf{a}}{r \sin \theta} \left\{ \frac{\partial(F_\phi \sin \theta)}{\partial \theta} - \frac{\partial F_\theta}{\partial \phi} \right\} + \frac{\mathbf{b}}{r} \left\{ \frac{1}{\sin \theta} \frac{\partial F_r}{\partial \phi} - \frac{\partial(r F_\phi)}{\partial r} \right\} + \frac{\mathbf{c}}{r} \left\{ \frac{\partial(r F_\theta)}{\partial r} - \frac{\partial F_r}{\partial \theta} \right\},$$

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2},$$

$$\nabla^2 \mathbf{F} = \mathbf{a} \left\{ \nabla^2 F_r - \frac{2F_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial(F_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial F_\phi}{\partial \phi} \right\} + \mathbf{b} \left\{ \nabla^2 F_\theta + \frac{2}{r^2} \frac{\partial F_r}{\partial \theta} - \frac{F_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial F_\phi}{\partial \phi} \right\} + \mathbf{c} \left\{ \nabla^2 F_\phi + \frac{2}{r^2 \sin \theta} \frac{\partial F_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial F_\theta}{\partial \phi} - \frac{F_\phi}{r^2 \sin^2 \theta} \right\}.$$

Rate-of-strain tensor:

$$e_{rr} = \frac{\partial u_r}{\partial r}, \quad e_{\theta\theta} = \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r}, \quad e_{\phi\phi} = \frac{1}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r}{r} + \frac{u_\theta \cot \theta}{r},$$

$$e_{\theta\phi} = \frac{\sin \theta}{2r} \frac{\partial}{\partial \theta} \left(\frac{u_\phi}{\sin \theta} \right) + \frac{1}{2r \sin \theta} \frac{\partial u_\theta}{\partial \phi}, \quad e_{\phi r} = \frac{1}{2r \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{r}{2} \frac{\partial}{\partial r} \left(\frac{u_\phi}{r} \right),$$

$$e_{r\theta} = \frac{r}{2} \frac{\partial}{\partial r} \left(\frac{u_\theta}{r} \right) + \frac{1}{2r} \frac{\partial u_r}{\partial \theta}.$$

Equation of motion for an incompressible fluid, with no body force:

$$\frac{\partial u_r}{\partial t} + \mathbf{u} \cdot \nabla u_r - \frac{u_\theta^2}{r} - \frac{u_\phi^2}{r} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left\{ \nabla^2 u_r - \frac{2u_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial(u_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right\},$$

$$\frac{\partial u_\theta}{\partial t} + \mathbf{u} \cdot \nabla u_\theta + \frac{u_r u_\theta}{r} - \frac{u_\phi^2 \cot \theta}{r} = -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left\{ \nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\phi}{\partial \phi} \right\},$$

$$\frac{\partial u_\phi}{\partial t} + \mathbf{u} \cdot \nabla u_\phi + \frac{u_\phi u_r}{r} + \frac{u_\theta u_\phi \cot \theta}{r} = -\frac{1}{\rho r \sin \theta} \frac{\partial p}{\partial \phi} + \nu \left\{ \nabla^2 u_\phi + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \phi} - \frac{u_\phi}{r^2 \sin^2 \theta} \right\}.$$